

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	570	717/124.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:03
S2	122	717/124.ccls. and (vision or image)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:04
S3	70	717/105.ccls. and (vision or image)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:04
S4	74	717/120.ccls. and (vision or image)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:04
S5	65	717/171.ccls. and (vision or image)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:24
S6	6455	"machine vision" or "robot vision" or "vision processing" and (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:27
S7	6416	"machine vision" or "robot vision" or "vision processing" and (process\$3 or anlaysz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) and (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and (tool or parameter)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 16:18

S8	1397	("machine vision" or "robot vision" or "vision processing" ) and (process\$3 or anlaysz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) and (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and (tool or parameter)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:36
S9	52	("machine vision" or "robot vision" or "vision processing" )same (process\$3 or anlaysz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3.) and tool and parameter	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:36
S10	52	("machine vision" or "robot vision" or "vision processing" ) same (process\$3 or anlaysz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (distributed or network\$3 or corba) and (send\$3 or receiv\$3 or analyz\$3 or select\$3 or acquir\$3 or transmit\$4 or collect\$3 or retriev\$4 or validat\$3 or verify\$3 or enter\$3 or input\$4 or choos\$3 ) and tool and parameter	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 15:37
S11	13	("5265014"   "5577165"   "5701400"   "5748974"   "5777614"   "5781179"   "5884294"   "5963911"   "6021403"   "6209788"   "6345111"   "6438523"   "6578005").PN. OR ("6779060").URPN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 16:18
S12	2812	("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 ) near5 ( filter\$3 or process\$3 or anlaysz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor ) and (distributed or network\$3 or corba or client or server )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 16:22

S13	225	("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 ) near3 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor ) same (distributed or network\$3 or corba or client or server )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/16 16:22
S14	20	("4511886"   "4943855"   "5103306"   "5111288"   "5144450"   "5202759"   "5218627"   "5227877"   "5236199"   "5430480"   "5444476"   "5509009"   "5510834"   "5521634"   "5548346"   "5598209"   "5619183"   "5625410"   "5652619"   "5793367").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 16:45
S15	22	("5926209").URPN.	USPAT	OR	OFF	2005/08/16 16:51
S16	372	(choic or choos\$3 or select\$3 ) near2 (vision or camera or optical) near2 (software or application or module or tool or component)	USPAT	OR	OFF	2005/08/16 16:52
S17	374	(choice or choos\$3 or select\$3 ) near2 (vision or camera or optical) near2 (software or application or module or tool or component)	USPAT	OR	OFF	2005/08/16 16:58
S18	16	(user or customer or purchaser or kiosk ) near3 (formats\$4 or manipulat\$3 or choice or choos\$3 or select\$3 ) near2 (vision or camera or optical) near2 (software or application or module or tool or component)	USPAT	OR	ON	2005/08/16 16:59
S19	12	("5940296"   "5956419"   "5963212"   "5999213"   "6088731"   "6125385"   "6161126"   "6256773"   "6278433"   "6298474"   "6380949"   "6522906").PN. OR ("6931602").URPN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 17:14
S20	1724	(camera or vision or image) adj simulat\$3	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 17:15
S21	22	((optical or camera or vision) adj simulat\$3 ) same parameter	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 17:15
S22	4	((optical or camera or vision) adj simulat\$3 ) same parameter same (network\$3 or server or client or corba or distributed wan or lan or internet )	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 17:17

S23	2	(( camera or vision) adj simulat\$3 ) same parameter and (network\$3 or server or client or corba or distributed wan or lan or internet )	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/16 17:23
S24	1	"6931602".pn.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/17 07:18
S25	520	consumer near3 (choice or choos\$3 or indicat\$3 or select\$3 ) same (imag\$3 or camera or photo or vision ) and (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet )	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 07:22
S26	195	consumer near3 (choice or choos\$3 or indicat\$3 or select\$3 ) same (imag\$3 or camera or photo or vision ) same (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet )	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 07:22
S27	53	consumer near3 (choice or choos\$3 or indicat\$3 or select\$3 ) near5 (imag\$3 or camera or photo or vision ) same (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet )	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 07:51
S28	1233	(consumer or user) near3 (choice or choos\$3 or indicat\$3 or select\$3 ) near5 (imag\$3 or camera or photo or vision ) same (remote\$2 or network or server or client or terminal or kiosk or lan or wan or internet ) and shar\$3	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 09:14
S29	24	silver.in. and cognex.as.	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 09:27
S30	0	visioneer.as. and blair.in.	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 09:28
S31	3794	blair.in.	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 09:28
S32	306	blair.in. and image	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 09:29
S33	2	blair.in. and "image management"	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 15:23

S34	0	"6931602".pn. and corba	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 15:25
S35	0	(( "6493677"; "6298474"; "54817126798531").pn. or "20030055745" or "20040100465") and corba	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 15:27
S36	240	("machine vision" or "image processing" or "vision processing" ) and corba	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 15:28
S37	1	("machine vision" or "image processing" or "vision processing" ) same corba	US-PGPUB; USPAT; USOCR	OR	ON	2005/08/17 15:28
S38	445	715/733.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:13
S39	11	715/733.ccls. and vision	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:18
S40	237	715/771.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:18
S41	25	715/771.ccls. and vision	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:20
S42	3380	709/217.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:20
S43	79	709/217.ccls. and vision	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:20
S44	844	719/315.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:21

S45	18	719/315.ccls. and vision	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:21
S46	2	719/319.ccls. and vision	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:22
S47	7	345/520.ccls. and vision	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:22
S48	305	345/520.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:22
S49	305	345/520.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:22
S50	106	719/319.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/18 08:22
S51	11830	("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor ) and (distributed or network\$3 or corba or client or server )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/02/07 15:45
S52	5473	("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) and (remot\$3 or distributed or network\$3 or corba or client or server ) and select\$3 and (client or customer ) near3 (information or account or data or records or password or id or identi\$6.)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:08

S53	2538	("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) same (remot\$3 or distributed or network\$3 or corba or client or server ) and select\$3 and (client or customer ) near3 (information or account or data or records or password or id or identi\$6 )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:08
S54	1453	("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) same (remot\$3 or distributed or network\$3 or corba or client or server ) and select\$3 and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:09
S55	943	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) same (remot\$3 or distributed or network\$3 or corba or client or server ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 select\$3 and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 09:44

S56	1423	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 (remot\$3 or distributed or network\$3 or corba or client or server ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 select\$3 and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:12
S57	154	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 ) near5 ( filter\$3 or process\$3 or anlayz\$3 or tuning or shap\$3 or scal\$3 or calibrat\$3 ) same (parameter or factor or type or number or value ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 (remot\$3 or distributed or network\$3 or corba or client or server ) and ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 select\$3 and (verify or verification or ensur\$3 or certify or certification or validat\$3) same ("machine vision" or "robot vision" or vision or optical or camera or gaz\$3 or imag\$3 ) near5 ( (client or customer ) near3 (information or account or data or records or password or id or identi\$6 ) )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:28
S58	2	"6931602".pn.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:31

S59	3	"6608628".pn.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/07 16:31
S60	12	("5940296"   "5956419"   "5963212"   "5999213"   "6088731"   "6125385"   "6161126"   "6256773"   "6278433"   "6298474"   "6380949"   "6522906").PN. OR ("6931602").URPN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/02/07 16:40
S61	6	remot\$3 near3 surgery same vision	US-PGPUB; USPAT; USOCR	OR	OFF	2006/02/07 16:42
S62	47	remot\$3 near3 surgery same camera	US-PGPUB; USPAT; USOCR	OR	OFF	2006/02/07 16:42
S63	13	("6298474").URPN.	USPAT	OR	OFF	2006/02/07 16:51
S64	6797	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) and ( select\$3 near5 tool ) and ( verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 09:48
S65	123	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) same ( select\$3 near5 tool ) same ( verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:09
S66	4873	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) same ( select\$3 near5 (tool or feature.) ) and ( verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:11
S67	1342	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) same ( select\$3 near5 (tool ) ) and ( verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:11
S68	517	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 ( select\$3 near5 (tool ) ) and ( verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:11

S69	400	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:12
S70	7214166	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) or (client or customer or user ) or (information or account or data or records or password or id or identi\$6 )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:14
S71	398	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and ( (parameter or factor or type or number or value ) or (client or customer or user ) or (information or account or data or records or password or id or identi\$6 ) )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:15
S72	391	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) and ( (client or customer or user ) or (information or account or data or records or password or id or identi\$6 ) )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:15
S73	338	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) and (client or customer or user ) and (information or account or data or records or password or id or identi\$6 )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:16

S74	291	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) and (parameter or factor or type or number or value ) and (client or customer or user ) same (information or account or data or records or password or id or identi\$6 )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 12:14
S75	272	S74 not S65	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 10:16
S76	3	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( select\$3 near5 (tool ) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 ( (client or customer or user ) near3 input) and (information or account or data or records or password or id or identi\$6 ) and (parameter or factor or type or number or value )	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 13:39
S77	746	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 ( (tool ) ) same (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 13:41
S78	16	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) same (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 13:51
S79	1717	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near3 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 13:52

S80	62	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) same (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 13:59
S81	46	S80 not S78	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 13:52
S82	269	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 (user or client or customer or employee)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 14:01
S83	269	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 (user or client or customer or employee) and (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 14:01
S84	269	("machine vision" or "robot vision" or vision or optical or camera or imag\$3 or sensor or computervision ) near5 (tool and data and (parameter or calibration or tolerance or setting or adjustment or control or slider) ) and (verify or verification or ensur\$3 or certify or certification or validat\$3) near3 (user or client or customer or employee) and (verify or verification or ensur\$3 or certify or certification or validat\$3)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 14:02

S85	259	S84 not S80 not S78	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/08 14:02
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